

Computer Sports Medicine, Inc., (CSMi)

HUMAC2015[®]/EMG
APPLICATION PROGRAM
User's Guide

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TABLE OF CONTENTS

SECTION 1. INTRODUCTION.....1-1
 Starting the Delsys Application1-1
 Starting the Noraxon Application.....1-3
SECTION 2. SELECTING THE EMG SYSTEM2-1
SECTION 3. SETTING THE AUXILIARY OUTPUTS.....3-1
SECTION 4. PROTOCOLS.....4-1
 Testing & Exercise4-1
SECTION 5. EMG SYSTEM PROTOCOLS5-1
 Defining the Configuration5-1
 Defining the Channels5-2
 Defining the Displays.....5-4
SECTION 6. REAL-TIME DISPLAY.....6-1
 Main Controls6-1
 Real-Time Plots.....6-1
SECTION 7. CALIBRATION7-1
SECTION 8. REPORTS.....8-1
 Plotted Data8-1
 Measured Parameters.....8-1
SECTION 9. EXPORTING EMG DATA.....9-1

LIST OF FIGURES

Figure 1 EMG System Selection2-1

Figure 2 Delsys Auxiliary Output Settings3-1

Figure 3 HUMAC Test Protocol With EMG Option.....4-1

Figure 4 EMG System Protocol Editor5-1

Figure 5 EMG Configurations5-1

Figure 6 EMG Channels - Default5-2

Figure 7 EMG Sensor Locations.....5-3

Figure 8 EMG Channels - Defined5-3

Figure 9 EMG Isokinetic Test Report.....8-2

SECTION 1.INTRODUCTION

This document describes the HUMAC/EMG System. The HUMAC/EMG is compatible with the Delsys Trigno and Noraxon myMOTION Systems.

Starting the Delsys Application

The Delsys Trigno Control Utility must be started before the HUMAC System.

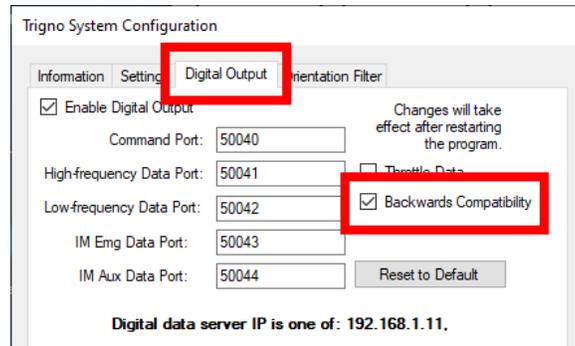
1. Start the Trigno Control Utility.



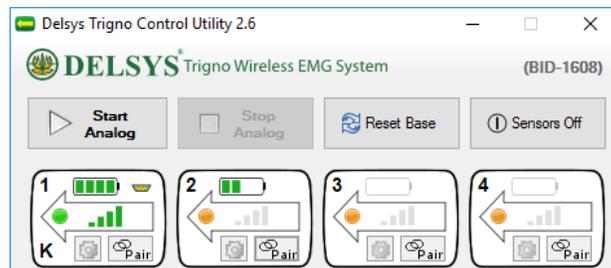
2. The first time you run the Trigno Control Utility you must configure Compatibility mode.
 - a. At the bottom of the Trigno utility, click the **CONFIGURE** button.



- b. From the **DIGITAL OUTPUT** tab, select **BACKWARDS COMPATIBILITY**.



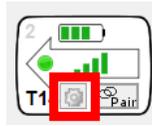
3. Pair the sensors with the Trigno Control Utility. **IMPORTANT:** The Trigno Auxiliary Adapter (K-type $\pm 5V$ Analog Adapter <https://www.delsys.com/trigno-analog-adapter>) must be paired as sensor number 1.



4. Complete the pairing of all sensors.
5. If you are using the new Avanti sensors, you must configure the sensor the first time it is paired with the Trigno utility.

- a. Analog Sensor (Channel 1).

- i. From the **SENSOR** icon, click the **GEAR** (configure) button.



- ii. Confirm the following settings from the **SENSOR SETTINGS** form.

The screenshot shows the 'Sensor Settings' form for 'Sensor 1'. The form includes the following information:

- Sensor 1**
- Type:** Analog Input Adapter
- ID:** 57137
- Firmware:** 40-34

Below this information, there is a section for 'Select Configuration Type' with three options: 'Analog x4', 'Analog x1', and 'Push Button'. The 'Analog x4' option is selected.

Underneath, there are four channels listed: 'Analog.A (V) ~2222 Hz', 'Analog.B (V) ~2222 Hz', 'Analog.C (V) ~2222 Hz', and 'Analog.D (V) ~2222 Hz'. Each channel has a corresponding colored square icon.

At the bottom, there are two settings: 'Rate' set to '2222Hz' and 'Bandwidth' set to 'DC-100Hz'.

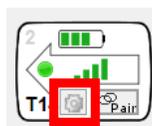
- iii. Set the **CONFIGURATION** to **EMG+ACC**

- iv. Set the **RATE** to **1926HZ**.

- v. Click the **APPLY AND CLOSE** button.

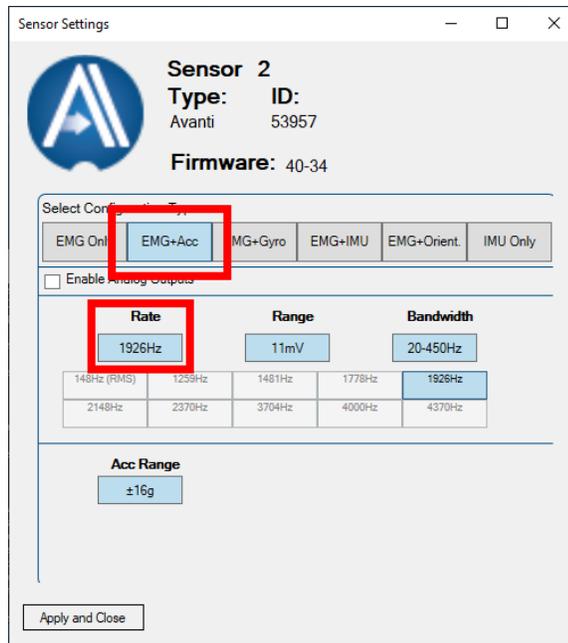
- b. EMG Sensors (Channel 2+).

- i. From the **SENSOR** icon, click the **GEAR** (configure) button.

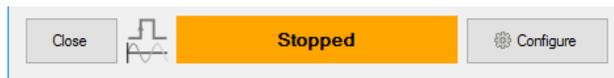


- ii. Set the **CONFIGURATION** to **EMG+ACC**

- iii. Set the **RATE** to **1926HZ**.



- iv. Click the **APPLY AND CLOSE** button.
 - c. **IMPORTANT:** The next time you use the Trigno system, simply start the Start the Trigno Control Utility and press the button (original design) or use the magnet (Avianti design) to re-pair the sensors. The Trigno utility will remember the previous settings. If you click the PAIR button on the Trigno Control Utility, you will need to set the configuration again.
6. The HUMAC connects to the Trigno system during active data collection. When you first start the HUMAC program, the Trigno utility will show “Stopped”.



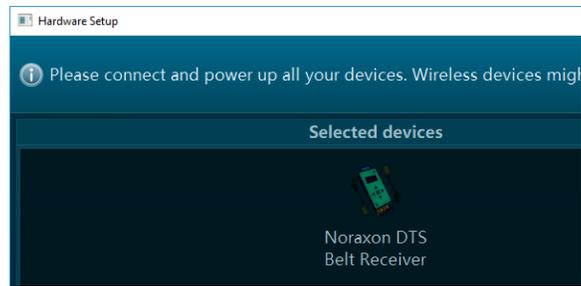
7. During the during active data collection the Trigno will show “Remote (1 user)”.



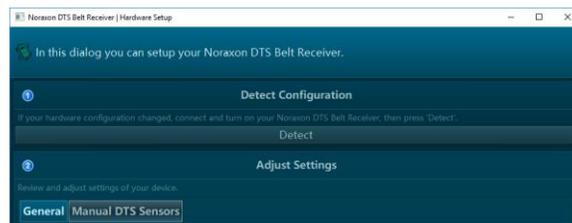
Starting the Noraxon Application

The Noraxon Connection Utility will automatically start when the HUMAC Program is started.

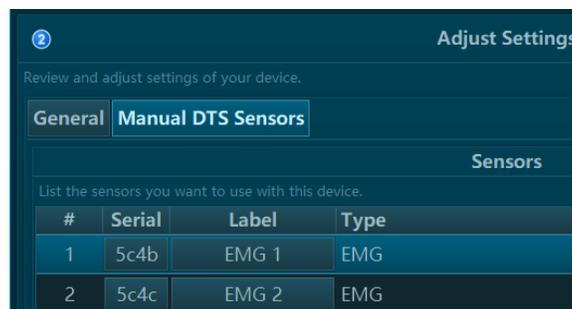
1. The HUMAC program will launch the Noraxon MR setup program.
2. Select your Noraxon hardware, e.g. NORAXON DTS BELT RECEIVER.



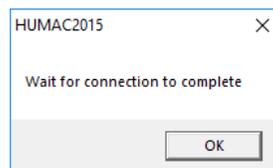
3. Click the **CONFIGURE** button.
4. From the Hardware Setup form, in the ❶ Detect Configuration area click the **DETECT** button.



5. The system should report the connection is successful. Click the **OK** button to continue.
6. In the ❷ Adjust Settings area click the **MANUAL DTS SENSORS** button and enter your sensor Serial Numbers. **Note:** The HUMAC Torque channel should be Sensor #1 and the Position Channel should be Sensor #2. The EMG sensors should start at #3.



7. Click the **OK** button to save your changes.
8. From the HUMAC Wait for connection form, click the **OK** button to continue.



SECTION 2.SELECTING THE EMG SYSTEM

To select the EMG system you will be using:

1. From the FILE menu, select **PREFERENCES**.
2. In the **EMG** area, **SYSTEM** picklist, select your EMG System.

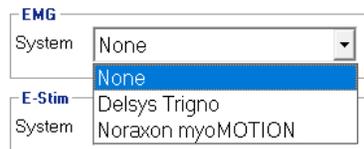


Figure 1 EMG System Selection

Note: You must select and EMG System to edit EMG protocols. The EMG System does not need to be connected to the HUMAC to edit protocols. The EMG System must only be connected to collect EMG data.

SECTION 3.SETTING THE AUXILIARY OUTPUTS

The Auxiliary Outputs should be set for the Delsys system.

1. From the **UTILITIES** menu, select **AUXILIARY OUTPUTS**.
2. Set the values as in Figure 2.
3. Click the OK button to save your changes.

| Position | Torque | Speed | Direction |
|---|---|---|---|
| <input checked="" type="checkbox"/> Enabled |
| Gain: 3000 | Gain: 570 | Gain: 2048 | Gain: 1024 |
| Offset: 0 | Offset: 0 | Offset: 0 | Offset: 0 |
| <input type="checkbox"/> Rectify | <input type="checkbox"/> Rectify | <input type="checkbox"/> Rectify | <input type="checkbox"/> Rectify |

OK Help

Figure 2 Delsys Auxiliary Output Settings

SECTION 4.PROTOCOLS

Testing & Exercise

When running a test or exercise session, the **PROTOCOL** form now includes an **EMG** option.

Protocol

Select: 3 Speed Protocol (60/180/240) | (5/12/2017-5/12/2017)

Rename: 3 Speed Protocol (60/180/240)

Set

Add Edit Delete Duplicate Up Down

EMG

Enabled

Setup

| Mode | Setting | Termination | Set Rest | Feedback | Protocol |
|--------------------|---------------|----------------|------------|------------------------|----------|
| Isokinetic Con/Con | 60 - 60 d/s | 5 Repetitions | 10 Seconds | Torque vs. Time Curves | |
| Isokinetic Con/Con | 180 - 180 d/s | 5 Repetitions | 10 Seconds | Torque vs. Time Curves | |
| Isokinetic Con/Con | 240 - 240 d/s | 15 Repetitions | 10 Seconds | Torque vs. Time Curves | |

OK Cancel Help

Knee Extension/Flexion Units: ft-lbs, Degrees, deg, d/s

Figure 3 HUMAC Test Protocol With EMG Option

Note: The EMG area will be disabled if no EMG System is selected from the **FILE, PREFERENCES** form.

- To include EMG data collection during a test, check the **EMG, ENABLED** checkbox.
- To edit the EMG protocol (sensor locations, displays) click the **SETUP** button. The HUMAC displays the EMG Editor form.

SECTION 5. EMG SYSTEM PROTOCOLS

The EMG System protocol editor allows you to define EMG settings which can be re-used across patients. In this example we'll define a "Quadriceps" **CONFIGURATION** with the following settings:

- Sample data from EMG Channel 1, EMG Channel 2, the NORM TORQUE and NORM POSITION channels.
- Display the EMG Channel 1 raw data, EMG Channel 1 RMS value, EMG Channel 2 raw data, NORM TORQUE data and NORM Position Data.

Note: You can also define EMG protocols from within the HUMAC System Protocol editor. (**UTILITIES PROTOCOLS**). EMG protocols defined inside the system protocol editor are tied to that specific system protocol.

1. From the **UTILITIES** menu, select **EMG PROTOCOLS**.
2. The HUMAC will display the EMG System Protocol Editor.

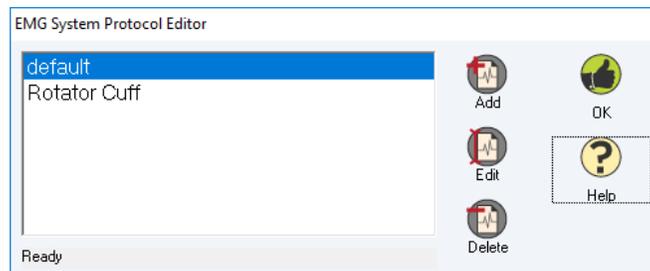


Figure 4 EMG System Protocol Editor

3. Click the **ADD** button.
4. The HUMAC duplicates the default EMG settings and displays the EMG Protocol Editor.

Defining the Configuration

The **CONFIGURATION** is the set of EMG hardware **CHANNELS** you will be sampling and real-time HUMAC **DISPLAYS** you want. **CONFIGURATIONS** are similar to extremity protocols which can be saved and re-used across patients.

1. In the **CONFIGURATIONS**, **NAME** field, enter "Quadriceps". The new name will be displayed in the list when you leave the field.

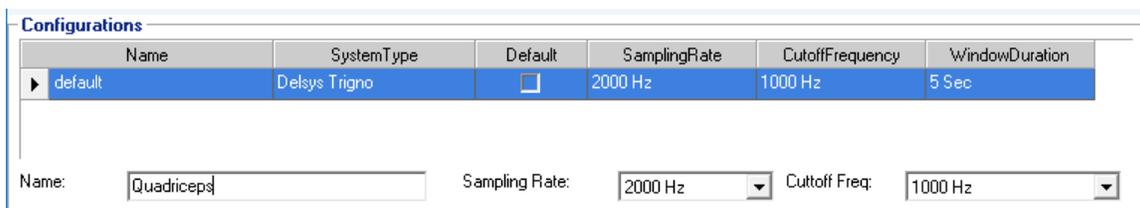


Figure 5 EMG Configurations

| ITEM | DESCRIPTION |
|-----------------------|---|
| NAME | The configuration name, e.g. “ <i>Quadriceps</i> ”. |
| SAMPLING RATE* | The hardware-based sampling rate. |
| CUTOFF FREQ* | The hardware-based cutoff frequency applied to all data channels. |

Note: The HUMAC EMG software is designed to support different EMG Systems. Not all EMG Systems include all hardware-based features listed below, e.g. **VARIABLE SAMPLING, FILTERING, and GAIN.**

Defining the Channels

The CHANNELS are the list of data channels supported by your EMG hardware.

In this example, we’ll place EMG2 on the Rectus Femoris and EMG3 on the Vastus Medialis. **Note:** EMG1 on the Delsys is used for the NORM Torque, Position, Velocity and Direction signals.

Channels

| Name | UserLabel | Location | Enabled | Digital Filter | Gain |
|-------|-----------|----------|-------------------------------------|----------------|------|
| ▶ TRQ | TRQ | | <input checked="" type="checkbox"/> | 1 | 1 |
| POS | POS | | <input checked="" type="checkbox"/> | 1 | 1 |
| VEL | VEL | | <input checked="" type="checkbox"/> | 1 | 1 |
| DIR | DIR | | <input checked="" type="checkbox"/> | 1 | 1 |
| EMG2 | EMG2 | | <input checked="" type="checkbox"/> | 1 | 1 |
| EMG3 | EMG3 | | <input checked="" type="checkbox"/> | 1 | 1 |
| EMG4 | EMG4 | | <input checked="" type="checkbox"/> | 1 | 1 |
| EMG5 | EMG5 | | <input checked="" type="checkbox"/> | 1 | 1 |

User Label:
 Digital Filter Len:
 Gain:
 Enabled
 Location:

Figure 6 EMG Channels - Default

1. In the **CHANNELS** area, select the **EMG2** row.
2. Enter “Rectus Femoris” in the **USER LABEL** field.
3. Click the **LOCATION ?** button to display a map of the sensor locations.

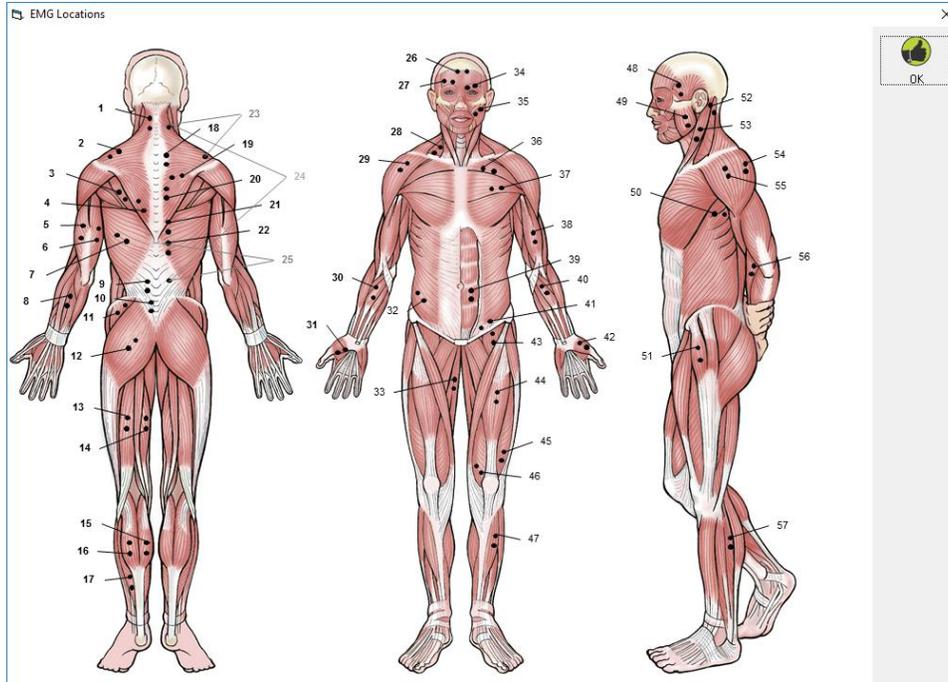


Figure 7 EMG Sensor Locations

4. We see the Rectus Femoris is location 44 on the sensor map. Click the **OK** button to close the form.
5. Enter 44 in the **LOCATION** field.
6. Continue the above process to define EMG3 as “Vastus Medialis”.
7. The channel display should look as follows.

| Channels | | | | | | |
|----------|-----------------|----------|-------------------------------------|----------------|------|--|
| Name | UserLabel | Location | Enabled | Digital Filter | Gain | |
| TRQ | TRQ | | <input checked="" type="checkbox"/> | 1 | 1 | |
| POS | POS | | <input checked="" type="checkbox"/> | 1 | 1 | |
| VEL | VEL | | <input checked="" type="checkbox"/> | 1 | 1 | |
| DIR | DIR | | <input checked="" type="checkbox"/> | 1 | 1 | |
| EMG2 | Rectus Femoris | 44 | <input checked="" type="checkbox"/> | 1 | 1 | |
| EMG3 | Vastus Medialis | 45 | <input checked="" type="checkbox"/> | 1 | 1 | |
| EMG4 | EMG4 | | <input checked="" type="checkbox"/> | 1 | 1 | |
| EMG5 | EMG5 | | <input checked="" type="checkbox"/> | 1 | 1 | |

User Label: Digital Filter Len: Gain: Enabled Location:

Figure 8 EMG Channels - Defined

| ITEM | DESCRIPTION |
|-------------------|---|
| NAME | The Channel Name. This is defined by CSMi for your EMG system. |
| USER LABEL | A custom name you can apply to the CHANNEL. |
| LOCATION | The EMG Sensor Location. When entering locations, click the ? button to display a muscle map with numbered locations. |
| ENABLED | The Channel is enabled for data collection. Note: Channels cannot be disabled with the Delsys system. |

| ITEM | DESCRIPTION |
|------------------------------|---|
| DIGITAL FITLER LENGTH | The EMG hardware-based digital filter length. |
| GAIN | The EMG hardware-based input gain. |

Defining the Displays

Display the EMG Channel 1 raw data, EMG Channel 1 RMS value, EMG Channel 2 raw data, NORM TORQUE data and NORM Position Data.

1. In the **CHANNELS** area, select the **TRQ** row.
2. In the Displays area, click the **ADD** button.
3. The HUMAC will add the **TRQ** channel to the list of **DISPLAYS**.

Displays

| Chan | Math | Offset | Gain | ABS | Invert | AC | +Limit | -Limit | +Thresh | -Thresh | Max | Min |
|-------|------|--------|------|--------------------------|--------------------------|--------------------------|--------|--------|---------|---------|--------------------------|--------------------------|
| ▶ TRQ | None | 0 | 1 | <input type="checkbox"/> | <input type="checkbox"/> | <input type="checkbox"/> | 32767 | -32767 | 20000 | -20000 | <input type="checkbox"/> | <input type="checkbox"/> |

4. Repeat the above adding the **POS** and **EMG2** channels.
5. Now we're going to add an **RMS** display of the EMG2 channel.
6. In the **CHANNELS** area, select the **EMG2** row and click the **ADD** button.

Displays

| Chan | Math | Offset | Gain | ABS | Invert | AC | +Limit | -Limit | +Thresh | -Thresh | Max | Min |
|--------|------------|--------|------|--------------------------|--------------------------|--------------------------|--------|--------|---------|---------|--------------------------|--------------------------|
| TRQ | None | 0 | 1 | <input type="checkbox"/> | <input type="checkbox"/> | <input type="checkbox"/> | 32767 | -32767 | 20000 | -20000 | <input type="checkbox"/> | <input type="checkbox"/> |
| PDS | None | 0 | 1 | <input type="checkbox"/> | <input type="checkbox"/> | <input type="checkbox"/> | 32767 | -32767 | 20000 | -20000 | <input type="checkbox"/> | <input type="checkbox"/> |
| EMG2 | None | 0 | 1 | <input type="checkbox"/> | <input type="checkbox"/> | <input type="checkbox"/> | 32767 | -32767 | 20000 | -20000 | <input type="checkbox"/> | <input type="checkbox"/> |
| ▶ EMG2 | RMS | 0 | 1 | <input type="checkbox"/> | <input type="checkbox"/> | <input type="checkbox"/> | 32767 | -32767 | 20000 | -20000 | <input type="checkbox"/> | <input type="checkbox"/> |

 Add
 Delete

Settings

Channel: **EMG2** Offset:
 Math: **RMS** Gain:
 Absolute Value Invert Signal AC Couple

Graph / LED Bar Scale

Upper Limit: + Threshold: Maximum Threshold
 Lower Limit: - Threshold: Minimum Threshold

7. In the **DISPLAYS** area, select the **EMG2** row. In the **SETTINGS** area set the **MATH** to **RMS**.
8. In the **CHANNELS** area, select the **EMG3** row and click the **ADD** button. The DISPLAYS area should look like the following.

Displays

| Chan | Math | Offset | Gain | ABS | Invert | AC | +Limit | -Limit | +Thresh | -Thresh | Max | Min |
|--------|------|--------|------|--------------------------|--------------------------|--------------------------|--------|--------|---------|---------|--------------------------|--------------------------|
| ▶ TRQ | None | 0 | 1 | <input type="checkbox"/> | <input type="checkbox"/> | <input type="checkbox"/> | 32767 | -32767 | 20000 | -20000 | <input type="checkbox"/> | <input type="checkbox"/> |
| PDS | None | 0 | 1 | <input type="checkbox"/> | <input type="checkbox"/> | <input type="checkbox"/> | 32767 | -32767 | 20000 | -20000 | <input type="checkbox"/> | <input type="checkbox"/> |
| EMG2 | None | 0 | 1 | <input type="checkbox"/> | <input type="checkbox"/> | <input type="checkbox"/> | 32767 | -32767 | 20000 | -20000 | <input type="checkbox"/> | <input type="checkbox"/> |
| EMG2 | RMS | 0 | 1 | <input type="checkbox"/> | <input type="checkbox"/> | <input type="checkbox"/> | 32767 | -32767 | 20000 | -20000 | <input type="checkbox"/> | <input type="checkbox"/> |
| ▶ EMG3 | None | 0 | 1 | <input type="checkbox"/> | <input type="checkbox"/> | <input type="checkbox"/> | 32767 | -32767 | 20000 | -20000 | <input type="checkbox"/> | <input type="checkbox"/> |

Note:

- You can modify the **DISPLAYS** by selecting the row and updating the values in the **SETTINGS** and **GRAPH / LED BAR SCALE** areas.
- When running a test, the HUMAC store the raw data for each selected **CHANNEL**. The selected **DISPLAYS** have no effect on the stored data. A channel does not have to be displayed to have the data stored.

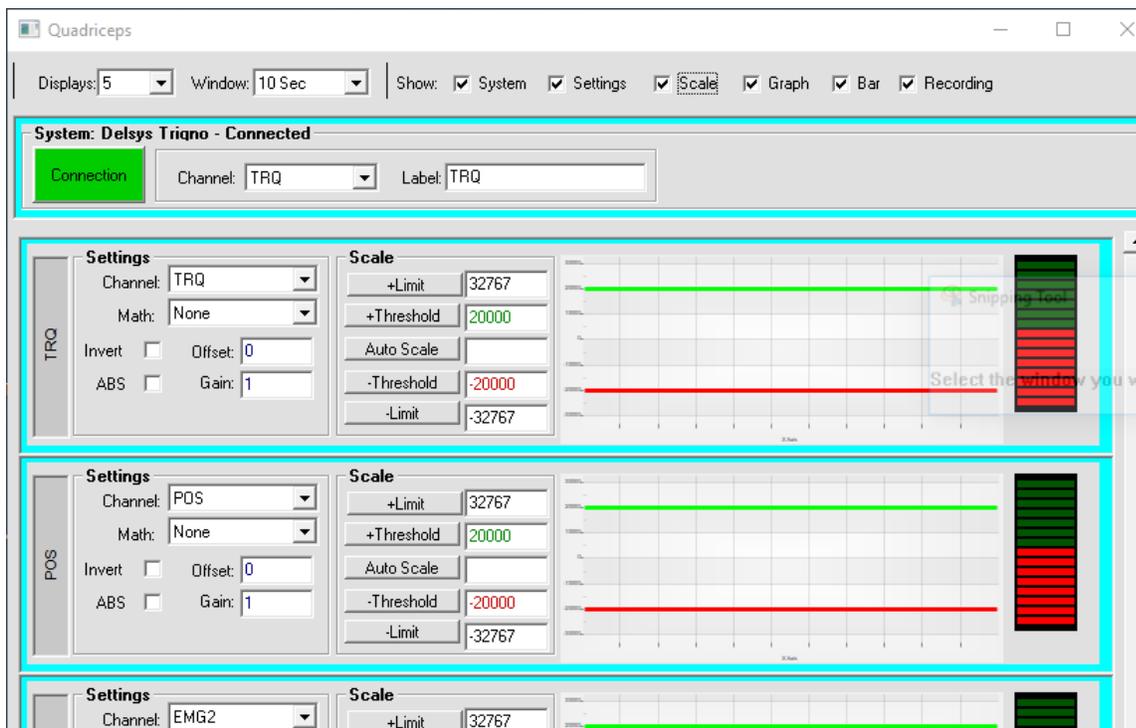
| ITEM | DESCRIPTION |
|--------------------------|--|
| CHANNEL | The EMG hardware channel number. |
| MATH | Math functions we want applied to the data, e.g. RMS, FIR filter. |
| OFFSET | Software-based offset (numeric value) applied to the displayed data. |
| GAIN | Software-based gain multiplier applied to the displayed data. |
| ABSOLUTE VALUE | Display the absolute value of the signal. |
| INVERT SIGNAL | Invert the displayed signal. |
| AC COUPLE | Apply an AC Coupling (7Hz high-pass) filter to the signal. |
| UPPER | Maximum Y-Axis value plot value. |
| +THRESHOLD | Upper Y-Axis marker displayed as a horizontal line on the plot. |
| -THRESHOLD | Lower Y-Axis marker displayed as a horizontal line on the plot. |
| LOWER | Minimum Y-Axis value plot value. |
| MAXIMUM THRESHOLD | When checked the +TREHSOLD will automatically track the maximum peak data value. |
| MINIMUM THRESHOLD | When checked the -TREHSOLD will automatically track the minimum peak data value. |

SECTION 6. REAL-TIME DISPLAY

1. The HUMAC utilizes a separate real-time display window which can be resized and moved independent of the HUMAC program.

Main Controls

At the top of the Real-Time display are the main controls.



| ITEM | DESCRIPTION |
|------------------|---|
| DISPLAYS | The number of real-time displays shown. The HUMAC defaults to the number defined in your CONFIGURATION. |
| WINDOW | The number of seconds of real-time data in each plot window. |
| SYSTEM | Display/hide the SYSTEM area. |
| SETTINGS | Display/hide the SETTINGS area. |
| GRAPH | Display/hide the real-time plots. |
| BAR | Display/hide the real-time bars. |
| RECORDING | Display/hide the RECORDING area (at the bottom of the form). |
| SCALE | Display/hide the SCALE area. |

Real-Time Plots

The HUMAC creates a separate real-time plot window for each **DISPLAY**.



| ITEM | DESCRIPTION |
|-----------------------------|---|
| USER LABEL | The USER LABEL defined in the CHANNELS display “Rectus Femoris”. This is listed vertically along the left side of the display. |
| SETTINGS | The hardware channel, math, offset and gain functions defined in the SETTINGS area of the DISPLAY form. |
| SCALE | The plot scale values defined in the GRAPH/LED BAR SCALE area of the DISPLAYS form. |
| +LIMIT | When +LIMIT is displayed the maximum y-axis value is set to the displayed value (32767). There are three ways to change this value: <ol style="list-style-type: none"> 1. Manually enter a new value in the data area. 2. Click the +LIMIT button to set the value in the data area to the maximum of the displayed data. 3. Click the AUTOSCALE button to set the +LIMIT and – LIMIT to the maximum of the displayed data +25%. |
| +THRESHOLD / MAXIMUM | Upper Y-Axis marker displayed as a horizontal line on the plot. There are two ways to change this value: <ol style="list-style-type: none"> 1. Manually enter a new value in the data area. 2. Click the +THRESHOLD button to change it to MAXIMUM. In this mode, the THRESHOLD tracks the MAXIMUM as a “lazy hand”. |
| AUTOSCALE | Click the AUTOSCALE button to set the +LIMIT and – LIMIT to the maximum of the displayed data +25%. |
| -THRESHOLD / MINIMUM | Lower y-axis marker displayed as a horizontal line on the plot. There are two ways to change this value: <ol style="list-style-type: none"> 1. Manually enter a new value in the data area. 2. Click the -THRESHOLD button to change it to MINIMUM. In this mode, the THRESHOLD tracks the MINIMUM as a “lazy hand”. |
| -LIMIT | When -LIMIT is displayed the minimum y-axis value is set to the displayed value (-32767). There are three ways to change this value: <ol style="list-style-type: none"> 1. Manually enter a new value in the data area. 2. Click the -LIMIT button to set the value in the data area to the minimum of the displayed data. <p>Click the AUTOSCALE button to set the +LIMIT and – LIMIT to the maximum of the displayed data +25%.</p> |

Note: When changes are made from this screen, the HUMAC will ask if you want to update your **CONFIGURATION** with the new values.

SECTION 7.CALIBRATION

Calibrating the EMG System allows the Delsys to report data in Foot-Pounds, Degrees and Degrees/Second. To calibrate the EMG System:

1. From the **EMG** menu, select **CALIBRATION**.

IMPORTANT: Before begging the *POSITION, VELOCITY, DIRECTION* calibration, the HUMAC will instruction you to remove all the weights. This is important as these calibrations are performed with the input adapter in CPM mode at 180 deg/sec.

EMG Calibration

TORQUE

- Move the Chair away from the Dynamometer (Monorail position 75).
Set the Chair Rotation to 0.
Set the Dynamometer Tilt to 0.
Set the Dynamometer Rotation to 0.
Lock the Dynamometer in the fully lowered position.
Position the Input Adapter at 12:00 (straight up).
Set the ROM Stops at Teal "U" and Gray "U"
Set the Knee/Hip Adapter to number 45. (Pin should click in-place.)
Rest the Input Adapter against the Teal "U" Stop.
- Move the Input Adapter toward Teal "Q" until it locks in-place.
- Place 100 pounds on the arm. (Weights #1, 2, 3 and 4).
- Remove all weight from the input arm assembly.

POSITION, VELOCITY, DIRECTION

- Begin Calibration (System will enter CPM mode at 180 deg/sec).

DONE

- Calibration completed.

 OK
  Cancel
  Help



SECTION 8.REPORTS

The HUMAC/EMG System includes a custom report. To generate an EMG report:

1. Click the **PATIENT** button and select a patient.
2. Click the **REPORT** button to open the reporting page.
3. Select the test. **Note: The EMG column indicates if EMG data was collected with the test.**

| Date | Machine | Pattern | Description | Test | RDats | LDat | EMG |
|--------------------|------------------|-------------------------------|---|-------------------------------------|-------------------------------------|-------------------------------------|-------------------------------------|
| 17/2017 6:56:57 AM | NORM | Knee Extension/Flexion | DATA FROM DELSYS | <input checked="" type="checkbox"/> | <input checked="" type="checkbox"/> | <input type="checkbox"/> | <input checked="" type="checkbox"/> |
| 8/2017 8:43:50 AM | NORM | Knee Extension/Flexion | DATA FROM DELSYS | <input checked="" type="checkbox"/> | <input checked="" type="checkbox"/> | <input checked="" type="checkbox"/> | <input checked="" type="checkbox"/> |
| 25/2017 9:27:50 AM | NORM | Knee Extension/Flexion | EMG | <input checked="" type="checkbox"/> | <input checked="" type="checkbox"/> | <input checked="" type="checkbox"/> | <input checked="" type="checkbox"/> |
| 25/2017 6:03:40 AM | Left MAT Balance | Extension Balance - Bilateral | Forceplate Base AP, Valid 87998 3498 A7 0 | <input checked="" type="checkbox"/> | <input checked="" type="checkbox"/> | <input type="checkbox"/> | <input type="checkbox"/> |

4. From the **REPORT TYPE**, select **ISOKINETIC EMG REPORT**.



5. Click the **PRINT** or the **PREVIEW** button.

Plotted Data

The HUMAC plots the Torque vs. Time and RMS EMG vs. Time.

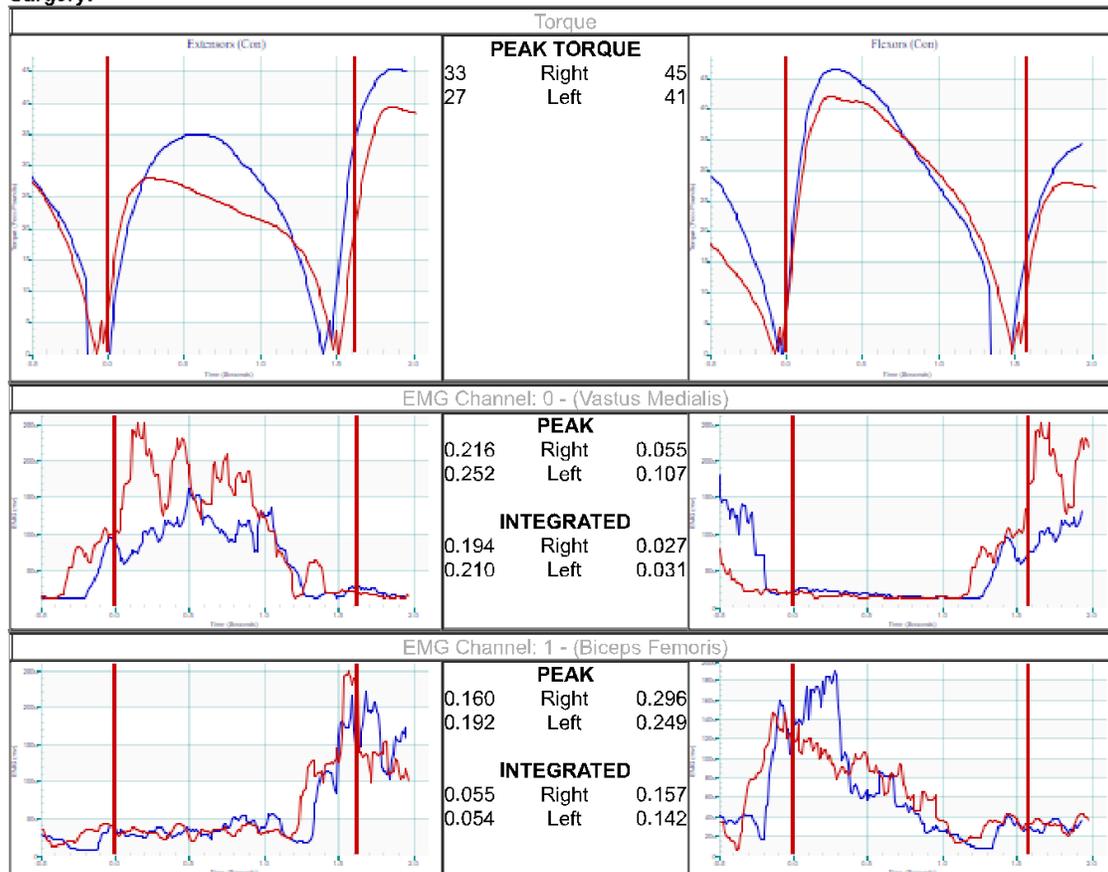
Measured Parameters

| PARAMETER | DEFINITION |
|-----------------------|------------------------------|
| Peak Torque | Peak Torque value. |
| Peak EMG | Peak of the EMG RMS value. |
| Integrated EMG | Area under the EMR RMS plot. |

HUMAC2015 Computer Sports Medicine, Inc.

Isokinetic EMG Report - Knee Extension/Flexion

Name: Potash, Robert L **ID:** 12345 **Right/Left:** 10/18/2017 10/18/2017
Birth date: 1/1/1970 **Involved Side:** Right & Left **Group 1:**
Height: 65 Inches **Preferred Side:** Right & Left **Group 2:**
Weight: 165 Pounds **Doctor:**
Gender: Male **Tester:** CSMi Tech
Diagnosis:
Surgery:



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Figure 9 EMG Isokinetic Test Report

SECTION 9.EXPORTING EMG DATA

The real-time data can be exported to a CSV file.

1. From the **DATABASE** menu, select **EXPORT**.
2. Select the row with the data you want to export and click the **EXPORT** button. *Note: The EMG column indicates if EMG data is included with the test.*

| Date | Machine | Pattern | Description | Test | RDdata | LDdata | EMG |
|-----------------------|---------------|--------------------------------|---------------------------------------|-------------------------------------|-------------------------------------|-------------------------------------|--------------------------|
| 1/15/2013 11:35:34 PM | HUMAC Balance | Standing Balance - Bilateral | CTSIB :15 Eyes Open Eyes Closed | <input checked="" type="checkbox"/> | <input checked="" type="checkbox"/> | <input type="checkbox"/> | <input type="checkbox"/> |
| 1/2/2013 10:27:34 AM | HUMAC Balance | Standing Balance - Bilateral | Concussion Test Eyes O/C, Surface N/P | <input checked="" type="checkbox"/> | <input type="checkbox"/> | <input type="checkbox"/> | <input type="checkbox"/> |
| 1/1/2013 1:42:46 PM | HUMAC Balance | Standing Balance - Bilateral | CTSIB :15 Eyes Open Eyes Closed | <input checked="" type="checkbox"/> | <input checked="" type="checkbox"/> | <input type="checkbox"/> | <input type="checkbox"/> |
| 3/29/2009 11:22:25 PM | NORM | Knee Extension/Flexion | 2 Speed Protocol (60/180) | <input checked="" type="checkbox"/> | <input checked="" type="checkbox"/> | <input checked="" type="checkbox"/> | <input type="checkbox"/> |
| 3/27/2009 11:41:24 AM | HUMAC 360 | Leg Vertical Jump - Unilateral | 5 Repts - 0, 10 Lbs Postion Bars | <input checked="" type="checkbox"/> | <input checked="" type="checkbox"/> | <input checked="" type="checkbox"/> | <input type="checkbox"/> |
| 3/27/2009 10:26:05 AM | HUMAC 360 | Leg Right/Left Cut | 10 Feet Right to Left 0, 10 lbs | <input checked="" type="checkbox"/> | <input checked="" type="checkbox"/> | <input type="checkbox"/> | <input type="checkbox"/> |
| 3/27/2009 10:09:23 AM | HUMAC 360 | Leg Vertical Jump - Unilateral | 5 Repts - 0, 10 Lbs Postion Bars | <input checked="" type="checkbox"/> | <input checked="" type="checkbox"/> | <input checked="" type="checkbox"/> | <input type="checkbox"/> |
| 3/27/2009 10:03:58 AM | HUMAC 360 | Arm Curl - Unilateral | Power Test 10, 12lbs 5, 10 Repts | <input checked="" type="checkbox"/> | <input checked="" type="checkbox"/> | <input checked="" type="checkbox"/> | <input type="checkbox"/> |
| 3/27/2009 10:01:25 AM | HUMAC 360 | Arm Curl - Unilateral | Power Test 10, 12lbs 5, 10 Repts | <input checked="" type="checkbox"/> | <input checked="" type="checkbox"/> | <input checked="" type="checkbox"/> | <input type="checkbox"/> |
| 3/27/2009 9:56:40 AM | HUMAC 360 | Arm Curl - Unilateral | Power Test 10, 12lbs 5, 10 Repts | <input checked="" type="checkbox"/> | <input checked="" type="checkbox"/> | <input checked="" type="checkbox"/> | <input type="checkbox"/> |
| 3/4/2008 9:59:53 AM | NORM | Knee Extension/Flexion | Isometric 90/60/30 degrees | <input checked="" type="checkbox"/> | <input checked="" type="checkbox"/> | <input checked="" type="checkbox"/> | <input type="checkbox"/> |

| | | | | | | | | |
|---------------------------|--|-----------|----------------|-----------------|-------|-------|------|------|
| [FILENAME] | C:\Users\Public\Documents\CSMi\HUMAC2015\EXPORT\Sample.csv | | | | | | | |
| [TEST DATE] | 5/12/2017 | | | | | | | |
| [TEST TIME] | 1:56:02 PM | | | | | | | |
| [CONFIGURATION NAME] | EMG Label Test - 1 | | | | | | | |
| [EMG APPLICATION INFO] | HUMAC EMG | | | | | | | |
| [EMG APPLICATION Version] | V01.00.02 | | | | | | | |
| [EMG TYPE] | Delsys Trigno | | | | | | | |
| [EMG FIRMWARE VERSION] | | | | | | | | |
| [EMG SAMPLING RATE] | 0 Hz | | | | | | | |
| [EMG CUTOFF FREQUENCY] | 1100 Hz | | | | | | | |
| [WSTACK TYPE] | N/A | | | | | | | |
| [WSTACK FIRMWARE VERSION] | | | | | | | | |
| [CHANNEL LABELS] | TRQ | POS | Rectus Femoris | Vastus Medialis | EMG4 | EMG5 | EMG6 | EMG7 |
| [CHANNEL LOCATIONS] | | | | | | | | |
| [CHANNEL GAINS] | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 |
| [CHANNEL DFILTER LENGTHS] | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 |
| [RECORD HEADER] | Record # | TimeStamp | TRQ | POS | EMG2 | EMG3 | EMG4 | EMG5 |
| [RECORD] | 1 | 0.001 | -1070 | 16243 | 31706 | 31604 | 0 | 0 |
| [RECORD] | 2 | 0.002 | 882 | 16243 | 31712 | 31742 | 0 | 0 |
| [RECORD] | 3 | 0.003 | 882 | 15992 | 31709 | 31742 | 0 | 0 |